Sizemore Academy (sizemoreacademy@gmail.com)

Insect Thing

My robot design uses two controllers and six legs. Two controllers allow for double the servo and motor ports, which in turn allows for more legs. It utilizes 8 servos and 6 motors, in addition to two slide sensors. It also uses a mechanical communication mechanism. It is designed to walk and did so successfully for 3.5 feet.



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