

- Hawaii Region

## Goals and Tasks for Botball 2019

### *1) Game Goals and Task*

- a. Get Botguy and the green (uninjured) and red (injured) people on our side of the table, 3/10/19
    - i. Grab BotGuy from the sky scraper, 3/10/19
    - ii. Save injured and uninjured people and bringing them to the disaster relief zone, 3/10/19
  - b. Put out burning fires 3/10/19
    - i. Bring firetruck to burning medical center, 3/10/19
    - ii. Bring firefighters to burning medical centers, 3/10/19
  - c. Build Botball game board 2/28/19
    - i. Get sections of board made 2/26/19
    - ii. Assemble the board 2/28/19
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### *2) Robot Building Goals and Tasks*

- a. Build robot claws to gather Botguy and injured and uninjured people , 3/12/19
  - i. has to be able to pick up the small people and the medical, food and water supplies, 3/10/19
  - ii. has to fit on robot(not too heavy, or too small), 3/12/19
- b. Using sensors, 3/20/19
  - i. The sensor has to be the right one for the situation for example the camera to find the color of the wounded people, 3/15/19
  - ii. Use the color sensor to pick up the right color figures for the situation, 3/20/19
- c. Building best design, 3/13/19

- i. Gather materials to build the appropriate size, 3/8/19
  - ii. Build a robot that can successfully drive and turn, 3/15/19
  - d. Testing design, 3/10/19
    - i. Test robot on game board to practice the real situations, 3/3/19
    - ii. Identify problems and make changes to the robot, 3/7/19
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### 3) *Programming Goals and Tasks*

- a. *We need to program the robot 2/22/19*
    - i. Program robot to go straight
      - 1.Type out a program 2/16/19
      - 2. Make the deadlines 2/16/19
    - ii.Program robot to make a u-turn 3/16/19
      - 1.Make the turn 3/14/19
      - 2. Extend turn 3/14/19
    - iii. Program robot to pick up cubes, 3/23/19
      - 1.extend existing program, 3/23/19
      - 2.find ticks per sec on robot arm, 3/23/19
  - b. Learn how to program the light sensor, *3/3/19*
    - i. Program light sensor to activate motors when light is detected, *3/3/19*
    - ii. Calibrate light sensor to ambient light, 3/3/19
  - c. Program camera, *3/3/19*
    - i. Learn how to program the camera, *3/5/19*
    - ii. Use camera to detect colors, *3/3/19*
  - d. Program motor and servos, *3/3/19*
    - i.* Learn how to program motor and servos, *3/3/19*
    - ii.* Program motors and servos to do different rotation, *3/6/19*
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#### 4) *Documentation Goals and Tasks*

- a. Complete first period documentation, 2/13/19
    - i. Complete Game Goals, Robot Building, and Programming tasks/goals, 2/13/19
    - ii. Discuss Schedule Conflict, 2/8/19
  - b. Complete second period documentation, 3/19/19
    - i. Gather Data about robot design from teammates, 3/5/19
    - ii. ii. Gather Data about program of robot from teammates, 3/12/19
  - c. Complete third period documentation, 4/25/19
    - i. Gather information from team and lessons learned, 4/23/19
    - ii. Discuss things we gain/learned from doing the Botball robotics, 4/23/19
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#### 5) *Schedule Conflicts*

- a. Feb 11, Teacher Institute Day, no school
  - b. Feb 18, President Day, no school
  - c. Mar 19, Good Friday, no school
  - d. March 18-22, Spring Break, no school
  - d. Mar 26, Kuhio Day, no school
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#### 6) Team Organization

##### *a. Schedule of Meeting Times:*

- i. Meet every class period (3x's a week)
- ii. Monday and Tuesday (after school)
- iii. 1x during spring break

*b. Division of Labor:*

- i. Mr. Anderson: Adult Team Leader
- ii. Maya Brown: Student Team Leader, Programmer, and builder
- iii. Raven Q, Tristan M, Brian S : Programer and builder
- iv. Charles W, Joshua S, Sean H, Leilani Phan: Builder
- ix. Leilani P, Isabelle D, Kathleen Y, Maya B : Documentation Team

*c. Conflict Resolution:*

If we have any disagreement we will handle it in the following ways:

- i. Present our views with our team members. Then we will try to make a compromise.
- ii. Ask student team leader to make final decision
- iii. If we still can't solve our disagreement, then we will talk to our adult team leader to how to solve