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printf("text\n");
motor (port#, power);
msleep (#milliseconds);
ao();
enable_servos();
set_servo_position(port#, position);
disable_servos ();
digital (port#);
analog (port#);
get_motor_position_counter(port#);
clear_motor_position_counter(port#);
```

```
//Prints text to display
//Turns motor on at % power specified
//Program waits specified number milliseconds
//All off, turns all motor ports off
//Moves servo in specified port to a set position
//Turns servo ports
//Refers to a specific digital port #
//Refers to a specific analog port #
//Get an analog  sensor reading
//Get the position of the motor in the specified port
//Clear the position of the motor in the specified port
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