

```
#include <kipr/wombat.h>
int main()
{
  printf("Going straight");

  motor (0,80); // straight
  motor (3,80);
  msleep (1000);

  return 0;
}
```

Type after the
printf ("Going straight");
function

Notes:

```
motor (0,80);
```

The port # your motor is
plugged into

Power of a wheel.
Power can only be from -100 to 100

The closer the wheels powers are to each other, the straighter it will go.



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