

```
from KT_Lib.KT_Lib import Tello  
import time
```

```
#Setup and Connect  
drone = Tello()  
drone.connect()
```

All lines starting with #
are comments and do not
effect outcome of program.

```
#Takeoff  
drone.takeoff()  
time.sleep(5)
```

These time amounts will
be different based on
what action the drone is
performing.

```
#In-Flight Commands  
drone.forward()  
time.sleep(5)
```

This is the place
where you should add
any commands to
control drone flight.

```
#Land and Disconnect  
drone.land()  
time.sleep(5)  
drone.disconnect()
```

