

1. Connect the yellow plugs. **DO NOT GO TO NETWORK/Settings**
2. Turn on the robot.
3. **Wait 5 minutes** for the robot to be ready.
4. **DO NOT GO** to Network/Wi-Fi settings.
5. Click on the **About** tab on your wallaby.
6. Find the **wallaby SSID (#)**, and **password**.
7. Find the **wallaby #** on your computers Wi-Fi, enter the **password**.
8. Go to a browser: Chrome, Firefox, **NOT Explorer**.
9. Type: **192.168.125.1:8888** in the address bar.
10. KISS Software suite will appear, be patient. Click **KISS IDE**.
11. Click “+” by Default user.
12. **Create** your own **user** or select your folder, example: Carol Folder. Include your name and the word folder for clarity.
13. **Add a project** to your folder.

```
#include <kipr/botball.h>
int main()
{
printf("Hello World!\n");

return 0;
}
```

Type after the
printf ("Hello World!\n");
function

It is normal to see limited connection or no Wi-Fi connection.

Your device Wi-Fi may keep switching back to the schools internet. You may want to select “Do Not Automatically Connect” to your school Wi-Fi.

