

# Variables

- Key Concepts
  - Understand what a variable is and how to use it.
- Pacing
  - Over several class periods.



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#### Standards



#### Goal:

- Students will familiarize themselves with the functions msleep() and motor()
- Students will understand how to move their robots in the following manner: forwards, backwards,

straight, circles, right and left turns

#### Standards:

Common Core State Standards Math Practices

CCSSMP1: Make sense of problems and persevere in solving them

CCSSMP2: Reason abstractly and quantitatively

CCSSMP4: Model with mathematics

CCSSMP6: Attend to precision

CCSSMP8: Look for and express regularity in repeated reasoning

Next Generation Science and Engineering Practice

- 1: Asking questions and defining problems
- 2: Developing and using models
- 3: Planning and carrying out investigations
- 4: Analyzing and interpreting data
- 5: Using mathematics and computational thinking
- 6: Constructing explanations and designing solution
- 7: Engaging in argument from evidence obtaining, evaluating, and communicating information



#### Standards Continued



#### **Standards Continued:**

2016 ISTE Standards

**Empowered Learner** 

1c: Students use technology to seek feedback that informs and improves their practice and to demonstrate their learning in a variety of ways.

1d: Students understand the fundamental concepts of technology operations, demonstrate the ability to choose, use and troubleshoot current technologies and are able to transfer their knowledge to explore emerging technologies.

Knowledge Constructor

3d: Students build knowledge by actively exploring real-world issues and problems,

developing ideas and theories and pursuing answers and solutions.

Innovative Designer

4a: Students know and use a deliberate design process for generating ideas, testing theories, creating innovative artifacts or solving authentic problems.

4b: Students select and use digital tools to plan and manage a design process that considers design constraints and calculated risks.

4c: Students develop, test and refine prototypes as part of a cyclical design process.

4d: Students exhibit a tolerance for ambiguity, perseverance and the capacity to work with open-ended problems.

**Computational Thinker** 

5a: Students formulate problem definitions suited for technology-assisted methods such as data analysis, abstract models and algorithmic thinking in exploring and finding solutions.



#### Intro to Variables: Activity 1



Prerequisite:

- Open a previous program that moves your robot somewhere or create a simple program that moves your robot somewhere.
- 2. Go to the next slide



#### Intro to Variables: Activity 1



What ports are your motors plugged into?







Great! Now, plug your motors into different motor ports without changing your code. Does your code work? Discuss with your partner why or why not.



#### Intro to Variables: Activity 1 Continued



• Modify your code to run with the new motor ports.

## WOW! That was exhausting. This would be a great place to use a variable.



#### Intro to Variables: Activity 1-Continued



Some reasons to use a variable:

- You don't have to *remember* which port # is left and which is right—the computer remembers for you!
- You don't have to *remember* how long to "sleep" for a 90-degree turn—the computer remembers for you!
- 3. If a motor port is changed, you can simply plug the motor into a different port, change the value of a variable in your program, and run your program.









A variable should go inside a block of code (i.e., inside the **{ }**) immediately after the starting curly brace (i.e., **{**).

What is int?

int stands for "integer".
This means that the
variable left\_motor
will have an integer value.

1. Creating a variable: int left\_motor

As long as your variable is meaningful and your team understands it can be named

whatever you want. Example: int l\_motor or int lm

- 2. Setting a variable: left\_motor = 1;
- 3. Using a variable: left\_motor

Click here for: Additional Data Types- Advanced learning



Example: creating, setting, and using variables

```
#include <kipr/botball.h>
int main()
{
  int left_motor; // 1. creating variables
  int right motor;
  left motor = 0; // 2. setting variables
  right motor = 3;
 motor(left motor,100); // 3. using variables
 motor(right motor, 100);
 msleep(1000);
 ao();
  return 0;
}
```



#### Sample of comments



/ arm = 0 // up = 1234 // down = 230 // claw= 3 // close=? //open=?

printf("Hello World\n");

return 0;

int open= ?;

}



- Copy the code from the <u>previous slide</u> and run the program.
- 2. Three things we *currently* know that we can apply variables to are:
  - a. motor ports
  - b. motor power

## int spd

C. duration (sleep time)

int time





Use the <u>"Tag You're It" assessment</u> from Unit 7, except you must specify the the **msleep** by

- 1. creating variables,
- 2. setting variables, and
- 3. using variables.





Use the <u>"Go Fetch" activity 9</u> from Unit 9, except you must specify the the claw positions by

- 1. creating variables,
- 2. setting variables, and
- 3. using variables.



# counter as an application of variables



# Assessments and Rubrics





Suggestions: *Understanding* rubric and or *Group Collaboration* 

